

Medium Access Control

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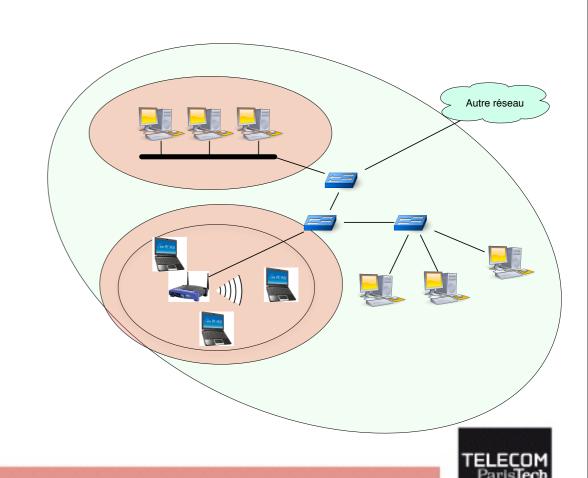
Collision vs. broadcast domains

Interconnection is done by inserting active elements in the network

- Increase maximum distance between two hosts
- Ease cabling
- Separate the network in independent zones

These devices define:

- Collision domains
 - Terminals need to organize to share a channel otherwise collisions will happen
- Broadcast domains
 - Terminals belong to the same "group" and are close to each other

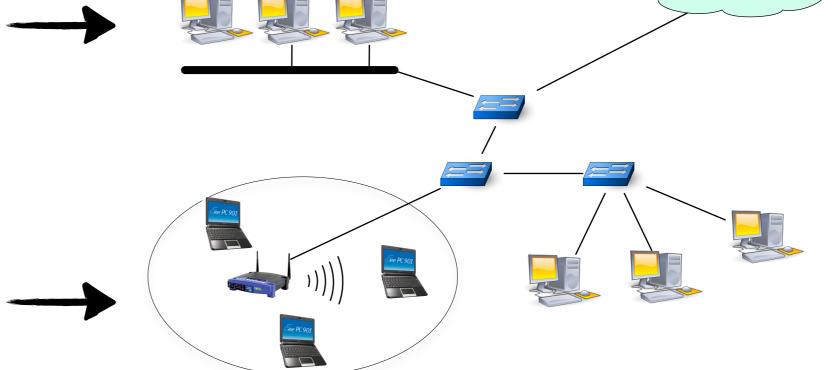


MAC layer role

- Organize concurrent transmissions on a shared link
 - Prevent collisions
 - Allow a fair access to the shared resource

- "Bus" type (HomePlug, "Old" Ethernet, ...)

- Wireless (Wi-Fi, Bluetooth, ...)



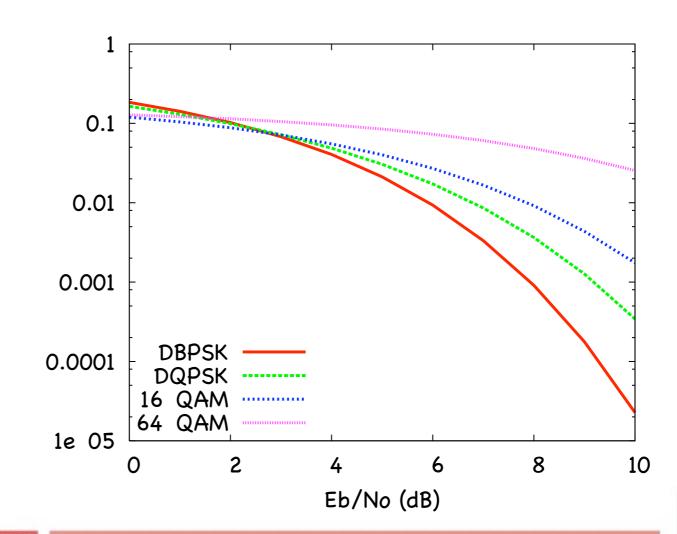


Autre réseau

Signal over noise ratio and collisions

- The PHY layer bit-error-rate
 - Depends on the received power (signal level)
 - Depends on the perturbation level (noise & interferences)
 - Defined by the used coding (modulation, ...)

 BER decreases when signal over noise ratio increases







Scheduled access



FDMA (Frequency Division Multiple Access)

 When multiple channels are available (e.g. frequencies), allocate one channel to each communication

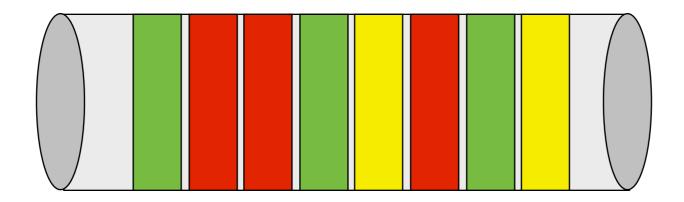


- FM radio-like mechanism
- Division provokes bandwidth loss: guard intervals between channels
- Requires receivers to be able to detect channels on the whole frequency band
- Insufficient when there are more emitters than available channels



TDMA (Time Division Multiple Access)

 Each communication can be granted the whole bandwidth for a limited amount of time



- Very suited to regular traffic (e.g. PCM sound)
- What happens when one station does not use the allocated time?
 - Performance loss in presence of irregular traffic
- Centralized mechanism the allocation needs to be done somewhere.





Random access



Early random access

- ALOHA: emit when a frame is ready, manage collisions
 - 18 % efficiency; 36 % when allowing emission only at precise moments (slotted ALOHA)
- Simple enhancement: CSMA = listen before talking
 - Kleinrock & Tobagi; early 1970's
- When an device wants to emit a frame:
 - It checks the medium to verify that no other signal occupies the medium
 - If the channel is free, it transmits
 - Otherwise, it waits until the channel gets free

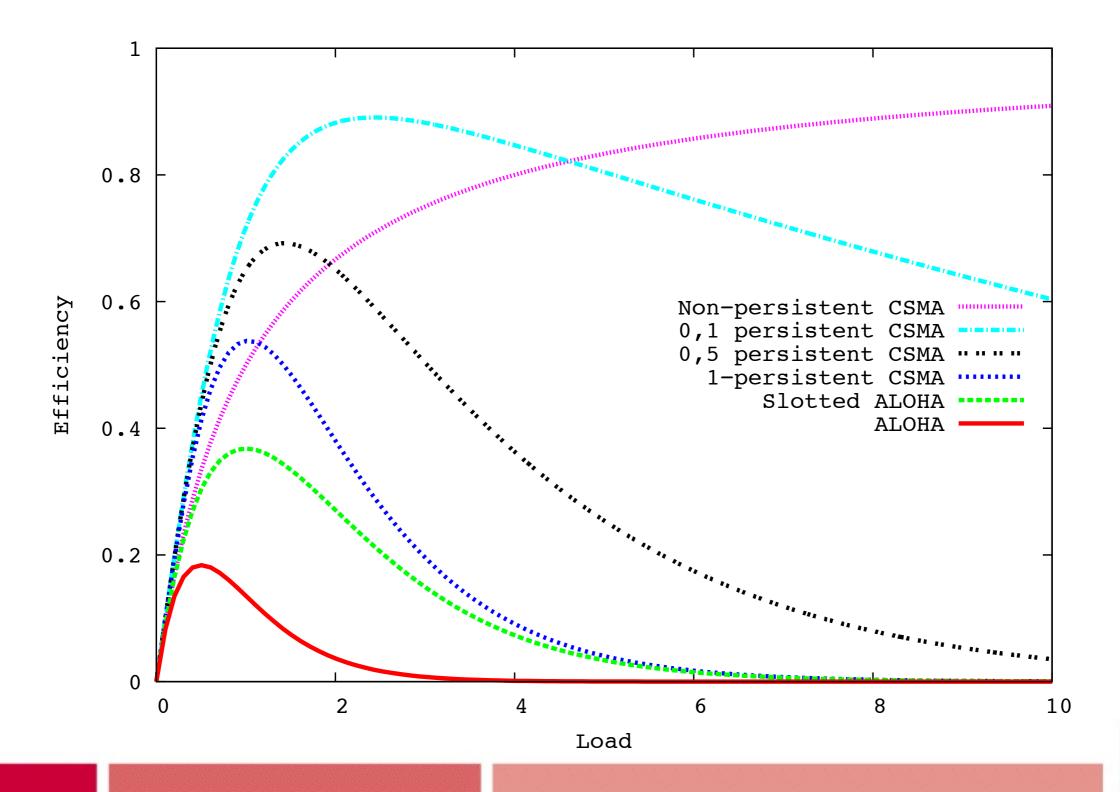


Radom access: desynchronizing emitters

- When the channel gets free, multiple emitters can be waiting
 - If they transmit as soon as the channel gets free => collision
- p-persistent CSMA: every station will emit with a probability p
- Slotted CSMA:
 - Each emitter draws a random time in an interval (random backoff)
 - They all wait the corresponding time
 - The first one to acquire the channel blocks the others



Random access: performance



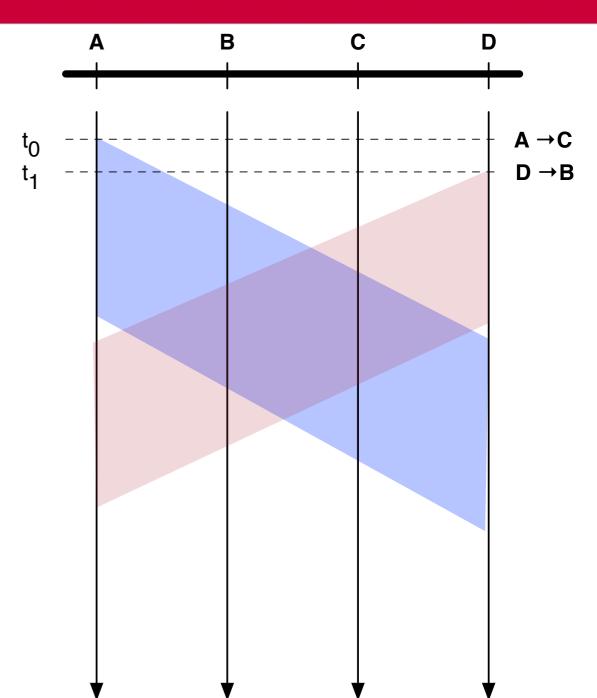


Propagation time influence

Collisions are always possible

 Two emitters can decide to start at the same moment

- There exists a vulnerability interval for every frame
 - All contenders must have noticed the signal
 - Depends on propagation time

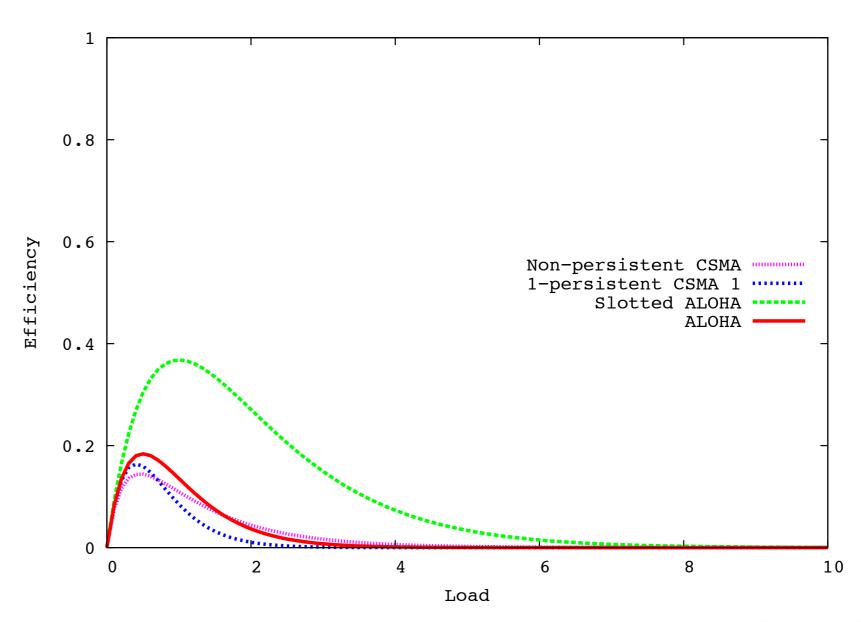




Propagation time influence (2)

CSMA algorithms performance depends on propagation time

- When propagation time approaches a frame transmission time, performance gets lower than ALOHA
 - Collisions
 - Waiting time
- ⇒ Some protocols limit maximum cable length







Ethernet on a bus: CSMA/CD



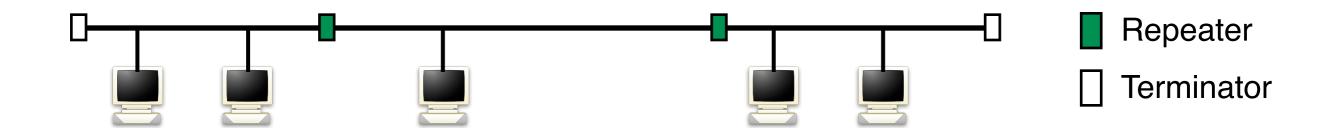




Scenario

Bus-like network (shared medium)

- Repeaters can re-generate signal and allow increasing the distance limit imposed by attenuation in the cable
- Terminators (resistors) at cable ends avoid echoes



Use of a CSMA-like protocol

Look at the voltage on the cable before performing any transmission



Collisions management - CSMA/CD

Emitter can detect itself when a collision happens:

- Compare emitted bits to the ones that pass on the medium.
- A difference indicates a collision

When collisions are detected, stop transmission

 If the emitted cannot decode its own signal, the receiver will not be able to decode it either.

Exponential backoff: re-emit frame after a random time:

- Draw an integer in a pre-defined interval (contention window): n ∈ [0; M]
- Wait for n times a constant time (slot time)
- If collision repeats, double the interval every time: $M \rightarrow 2.M \rightarrow 4M...$



Ethernet - an emitter's point of view

- Receive a packet from the network layer
- Encapsulate it in an Ethernet frame
- Listen to the channel
 - If the channel is free, transmit
 - Otherwise, wait until it is free plus 96 bit-times before transmitting (9,6 μ s at 10 Mb/s)

During transmission

Listen to the medium to detect collisions

In case of collision

- Stop immediately the transmission
- Send a 48 bits jamming signal

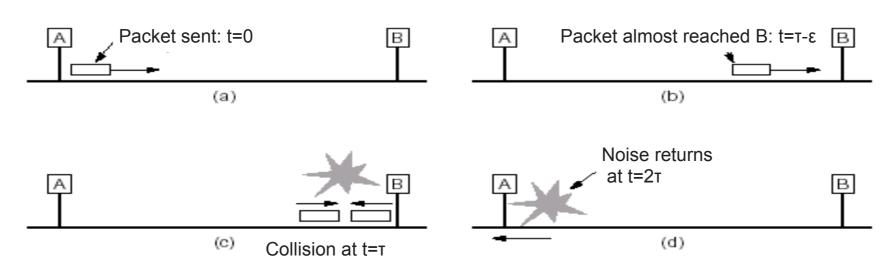
After nth collision, exponential backoff:

- Draw a random number k in $[0; 2^m 1]$ (m = min (n, 10))
- Wait k times 512 bit-times (i.e. 51,2 μ s at 10 Mb/s)
- Limit the number of retries to 15



Why a 48 bits jamming signal?

- All other terminals need to detect the collision
 - Example: A emits, B emits just before A's signal reaches B
 - B stops right away, after a few bits
 - A does not necessarily detect the collision (too low energy, A's frame already finished, ...)
- Jamming signal ensures every collision is detected



Source: A. Tannenbaum - Networks



Ethernet frame format

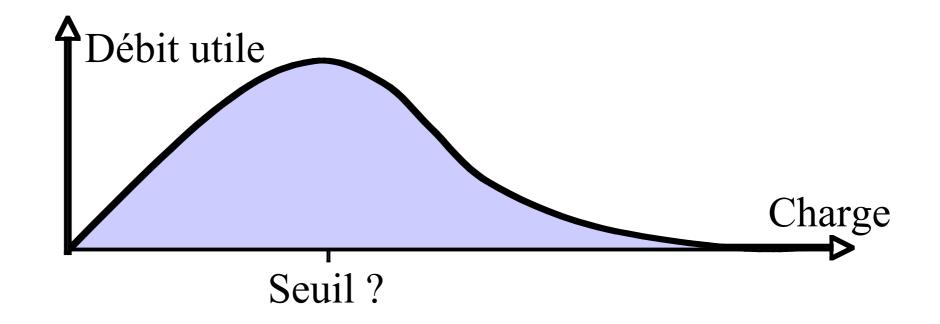
Preamble @ dest @ src type Data Checksum

- Preamble (8 bytes)
 - 7x (10101010) for synchronization + 1x (10101011)
- @ dest, @src (2 x 6 bytes)
 - peers MAC addresses
- Type (2 bytes)
 - Identifies the network layer protocol (IP, IPX, ...)
- Data (48 to 1500 bytes)
 - If less than 48 bits, add padding
- Checksum (4 bytes)
 - CRC based on the @dest to data part
- Emission order
 - Bytes: in the left to right order (preamble sent first)
 - Bits: LSB (little endian)



Performance

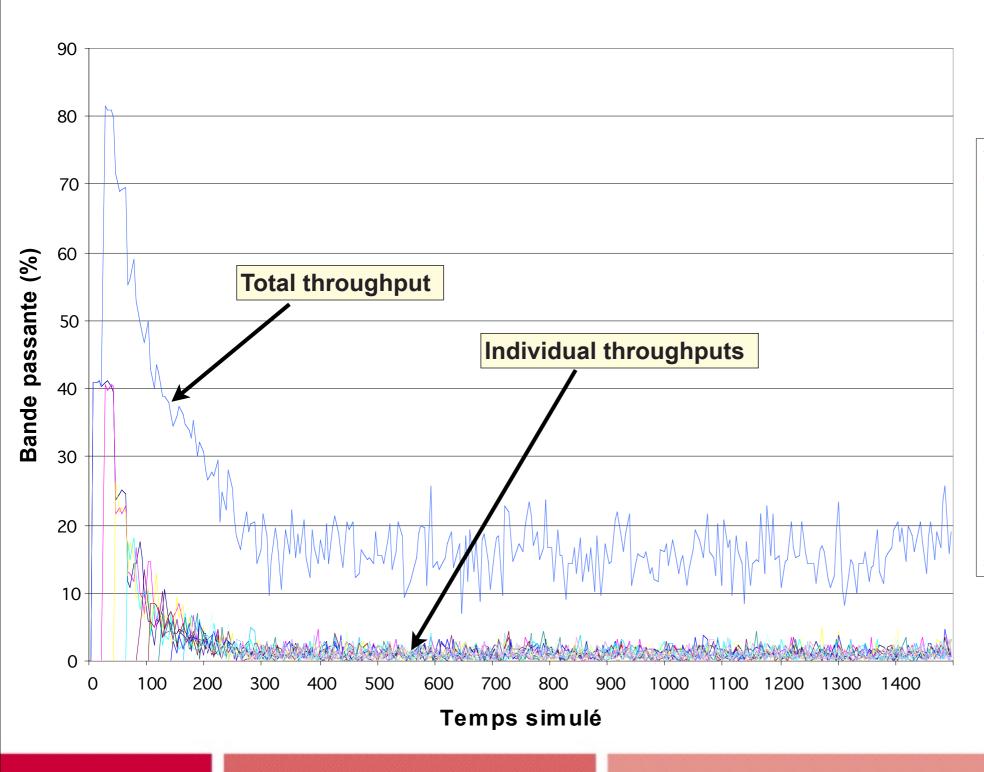
- Depends directly on the collision probability
 - If there are too many collisions, terminals spent their time waiting



- Low load: optimal performance (No waiting time)
- High load: collapse



Performance collapse simulation



Simulation: periodical addition

UDP 1 UDP 2

UDP 3 UDP 4

UDP 5

UDP 6
UDP 7

UDP 8

UDP 9 UDP 10

UDP 11 UDP 12

UDP 13 UDP 14 UDP 15

TCP

TOTAL

of emitters, each trying to occupy 40% of the medium capacity



Ethernet today

Topologies have changed

- No bus-like architectures anymore, mostly switched Ethernet
- CSMA/CD unused today

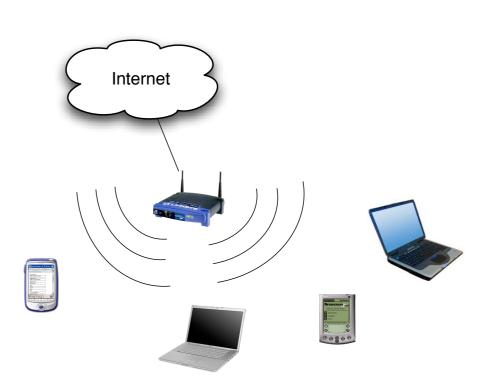
Throughput increase

- Fast Ethernet (100 Mb/s)
- Gigabit Ethernet
 - Standard in most of today's computers
- 10 Gb/s Ethernet coming





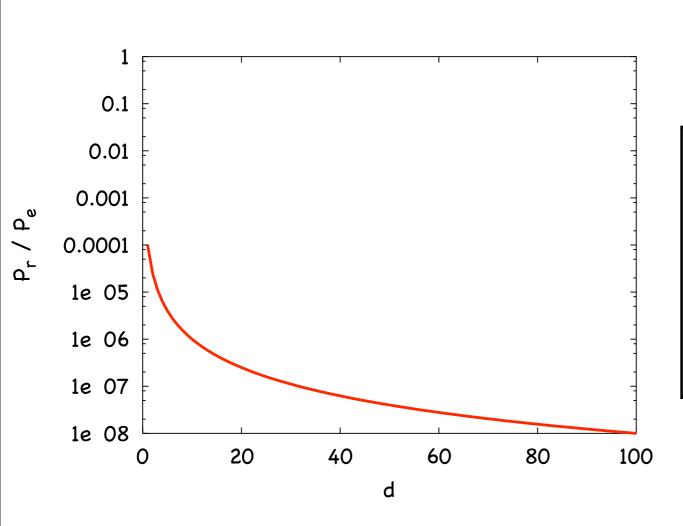
Wi-Fi (IEEE 802.11) — CSMA/CA





Wireless (radio-frequencies) attenuation

Free space (idealistic conditions):



$$P_r = \left(\frac{\lambda^2}{16 \cdot \pi^2 \cdot d^2}\right) \cdot G_e \cdot G_r \cdot P_e$$

Pr: Received power

Pe: Emitted power

λ: wavelength

d: distance between emitter and receiver

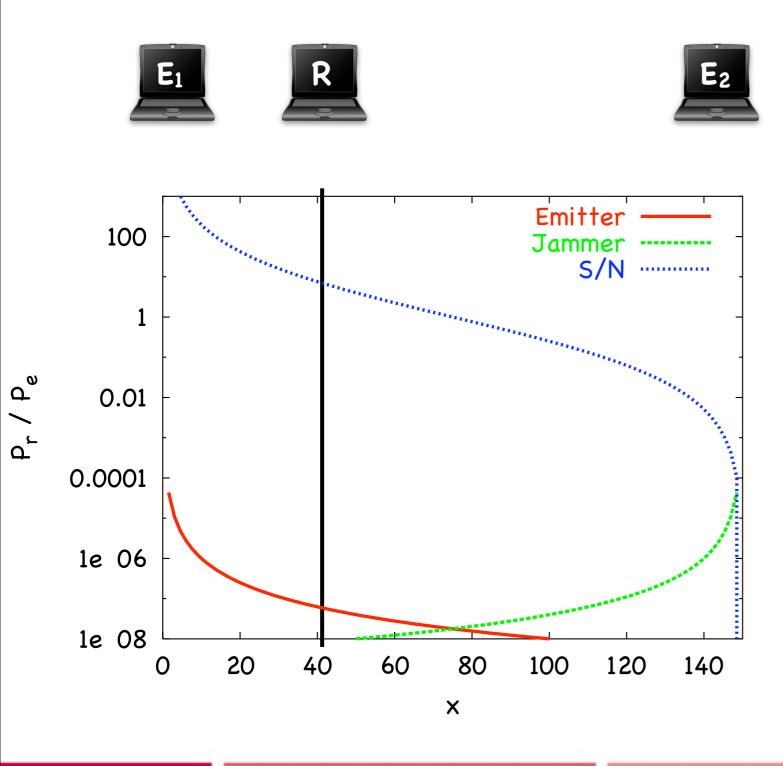
Gr: receiver antenna gain

Ge: emitter antenna gain

 Signal level decreases in function of the square of the distance (best case)



Wireless collisions

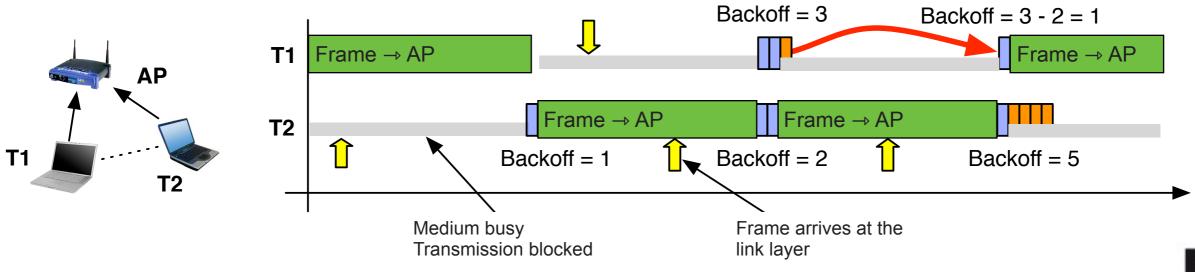


- The emitter cannot detect collisions
 - Impossible to stop an ongoing frame transmission
- Explicit
 acknowledgments
 required
 - Wi-Fi: stop & wait



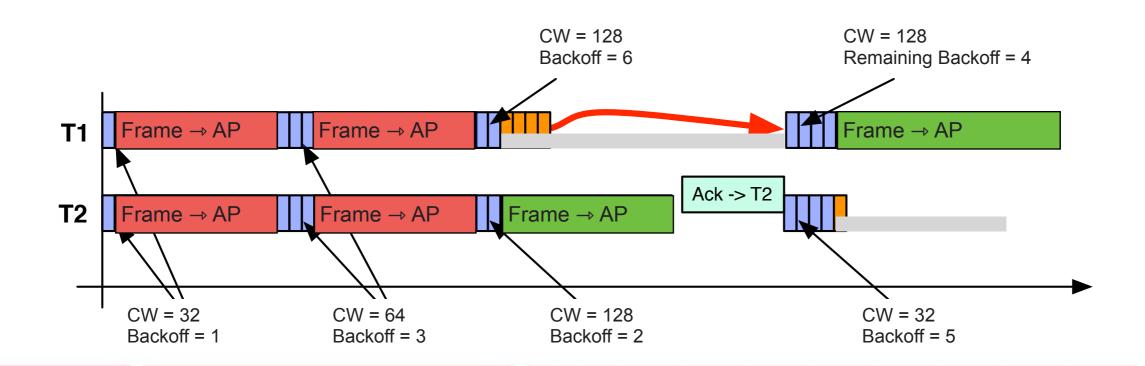
Frame emission

- A frame transmission that starts will be ended (no stop)
- CSMA/CA: a classical, yet cautious CSMA flavor
 - When the medium is free, emitter always waits a random backoff
 - Ethernet: one try without waiting
 - The initial contention window is larger than Ethernet's (16 vs. 2)
 - When contention is lost, we keep the backoff value for the next try
 - There is a backoff between two successive frames
 - Allow other emitters to win the contention



Acknowledgments & retransmissions

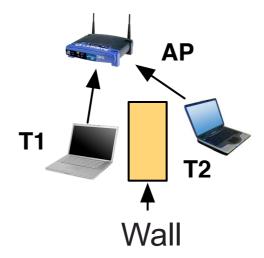
- Every unicast frame must be acknowledged explicitly
 - Stop-and-wait explicit acknowledgments
- Retransmission when no acknowledgment arrives
 - Contention window size is doubled (max: 1024)
 - Cancel after a limited number of tries (between 4 and 7)



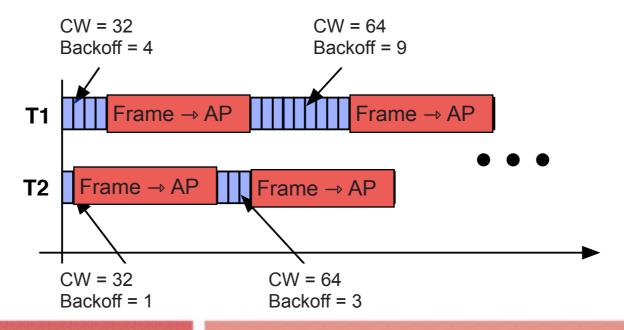


The hidden node scenario

- Everything depends on the carrier detection
 - What happens when two emitters do not sense their mutual emissions?



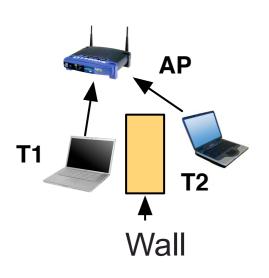
If frames are too long, repeated collisions:

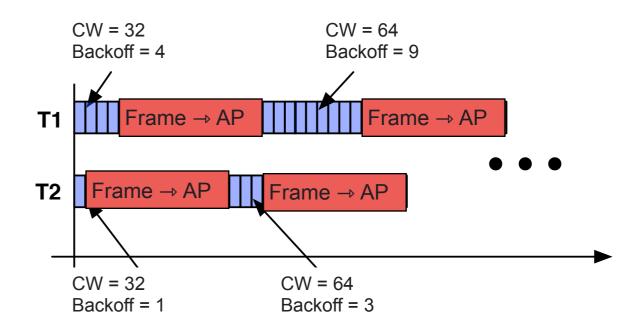




Origin of the issue

The problem comes from the ratio between the average backoff and the frame transmission time





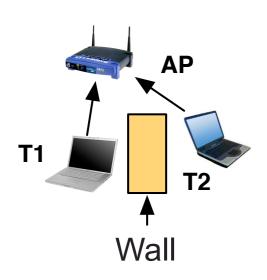
Example: 1500 bytes at 11 Mb/s: 343 μ s

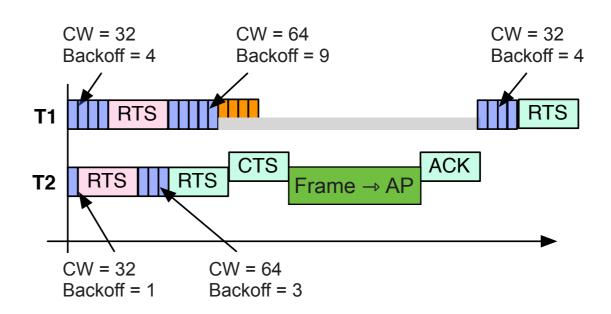
CW	32	64	128	256	512	1024
Average backoff	310 µs	630 µs	1270 µs	2550 µs	5110 µs	10230 μs



RTS-CTS exchange

- Solution: precede the large frames emission by a short exchange:
 - RTS (Request To Send) from emitter to receiver (ask for authorization to send)
 - CTS (Clear To Send) from receiver to emitter (authorization granted)
 - Broadcast RF medium: the answer notifies all neighbors in range





- CTS contains the expected transmission time
 - Other emitters are blocked during this time



MAC layer performance

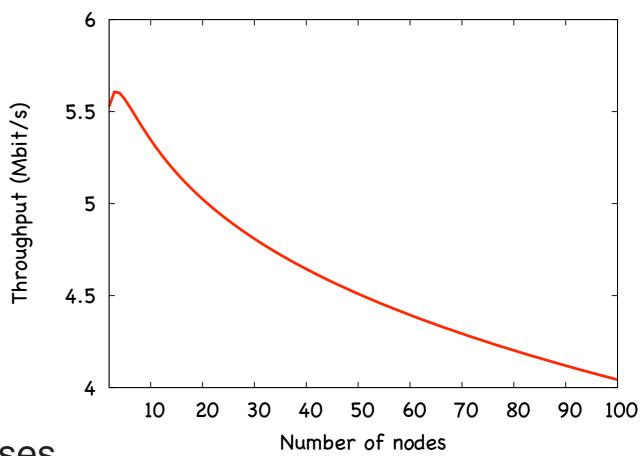
Exact performance: probabilistic calculation (Markov chains)

High overhead

- Backoff, RTS, CTS, acks, ...
- Efficiency around 50% to 60%

When the number of emitters increases

- backoffs are spent in parallel
 ⇒ performance gain
- Quickly the collision probability increases
 performance decrease





Access equity = throughput fairness?

Wi-Fi proposes multiple throughputs

- 1, 2, 5.5, 11, 18, 27, 33, 54, ... Mbit/s
- Different modulations ⇒ different ranges and noise reactions
- Each station seeks the best compromise between losses and throughput

A 1 Mb/s station vs. all others at 54 Mb/s:

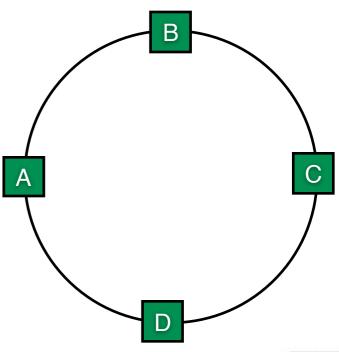
- Emission on the same shared channel
- Wi-Fi grants packet-level fairness
- Each station can only emit one frame per turn
- 1 Mb/s transmission increases turn duration
- Everybody gets a 1 Mb/s throughput





Decentralized collision-free protocols

Token Ring example





Token Ring — Introduction

History

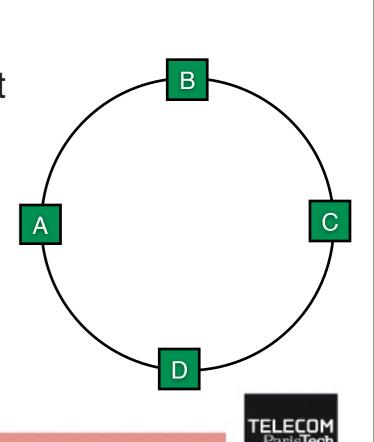
- Created in 1969
- Introduced by IBM in the 1980's
- Standardized by IEEE (IEEE 802.5) in 1985
- Not deployed anymore today

Ring-like topology

 All stations are connected to neighbors by point-to-point links

Typical throughputs

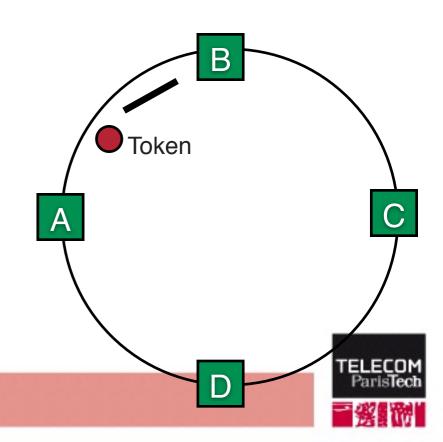
- IBM: 4 Mb/s
- IEEE 802.5: 16 Mb/s



Access technique

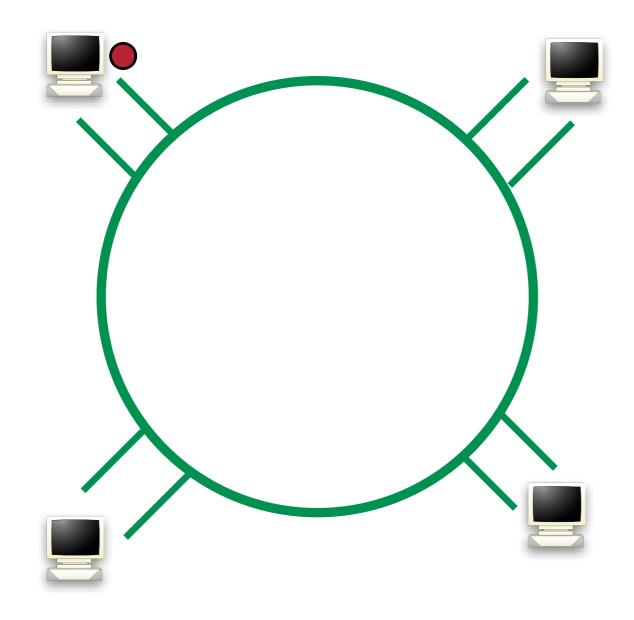
One-direction ring

- Use of a virtual token to organize access
 - Only the station that possesses the token is allowed to transmit
 - No collision
 - Station passes the token to its neighbor once the transmission is finished



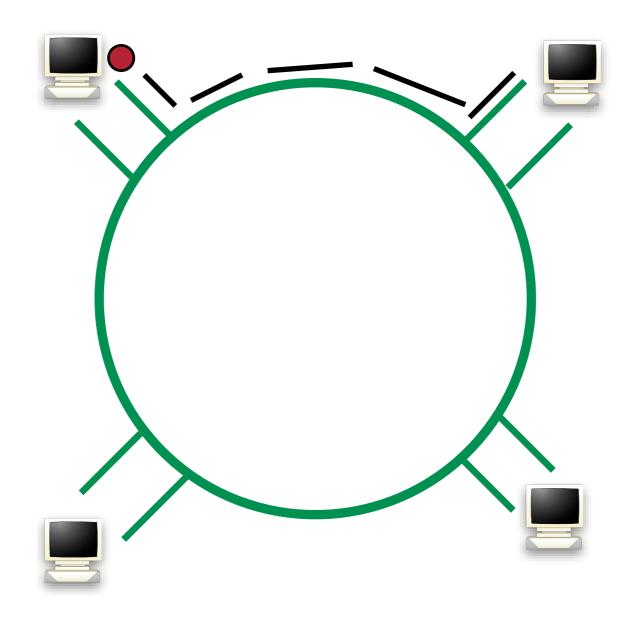


Token passing





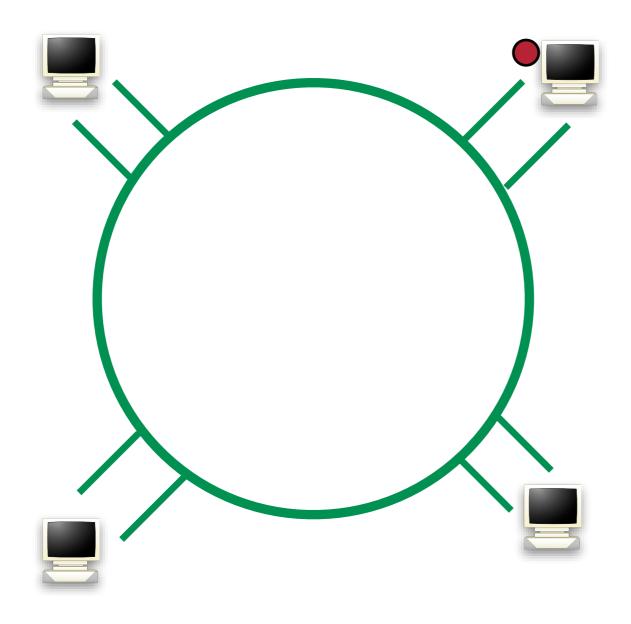






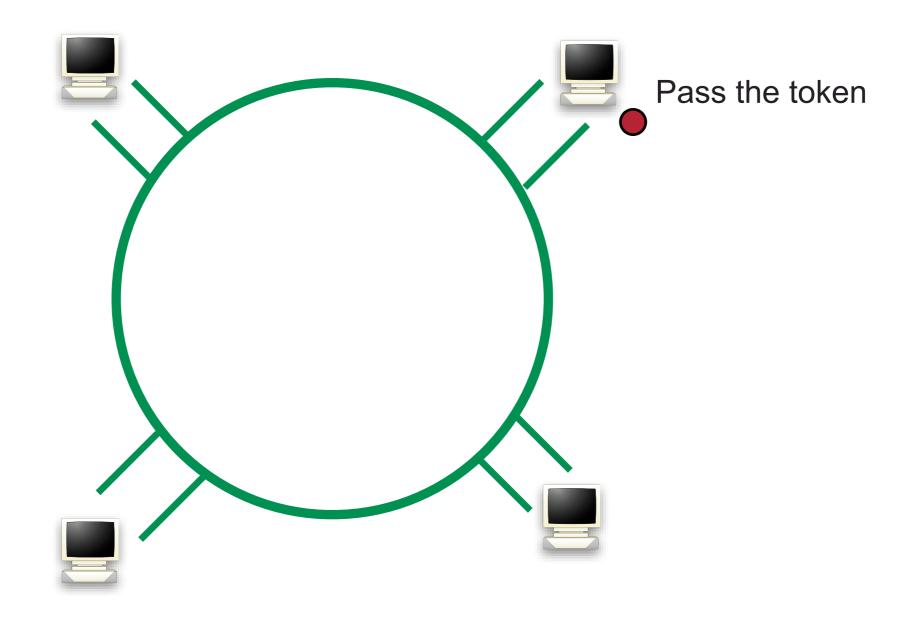


Frame awaiting?



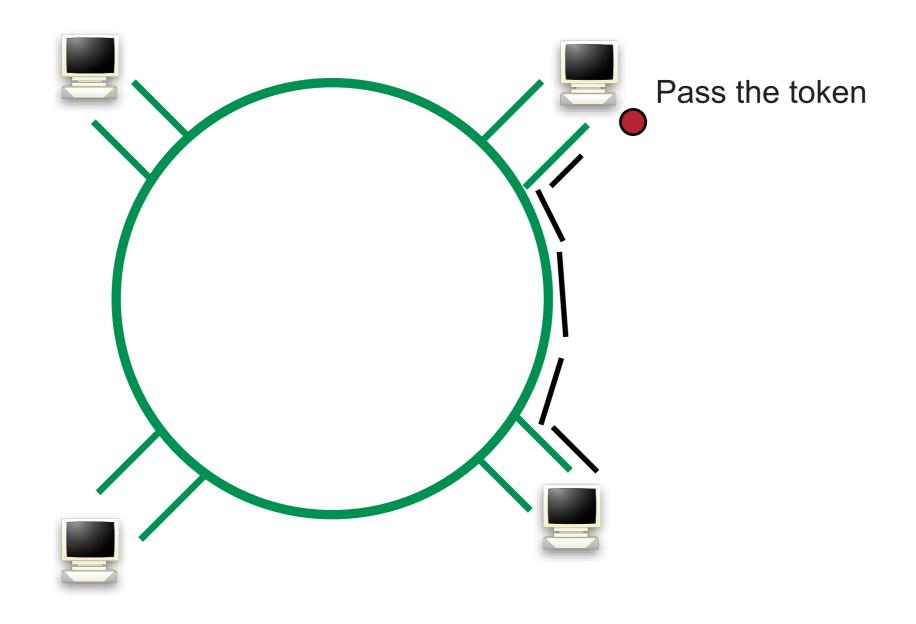




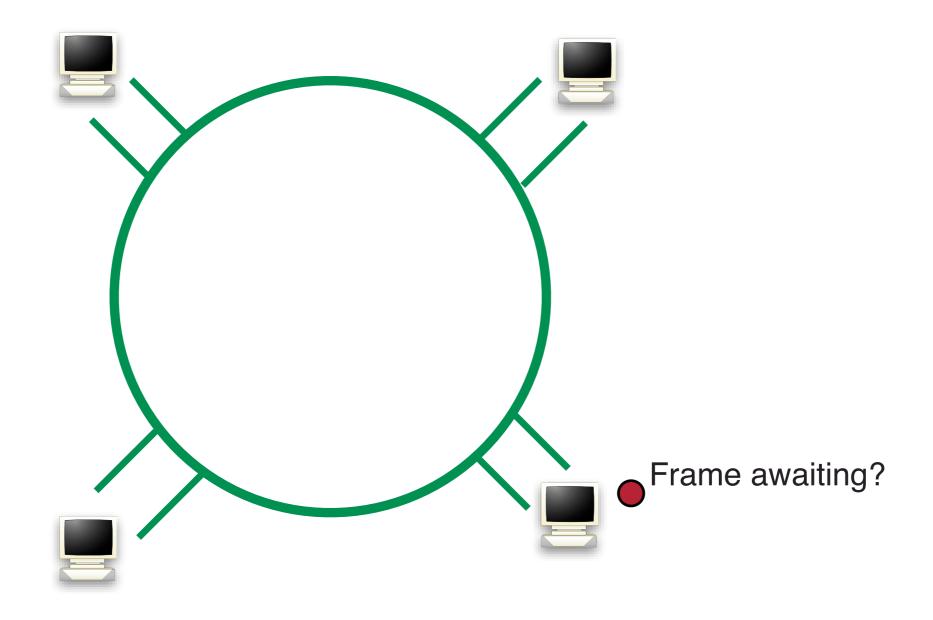




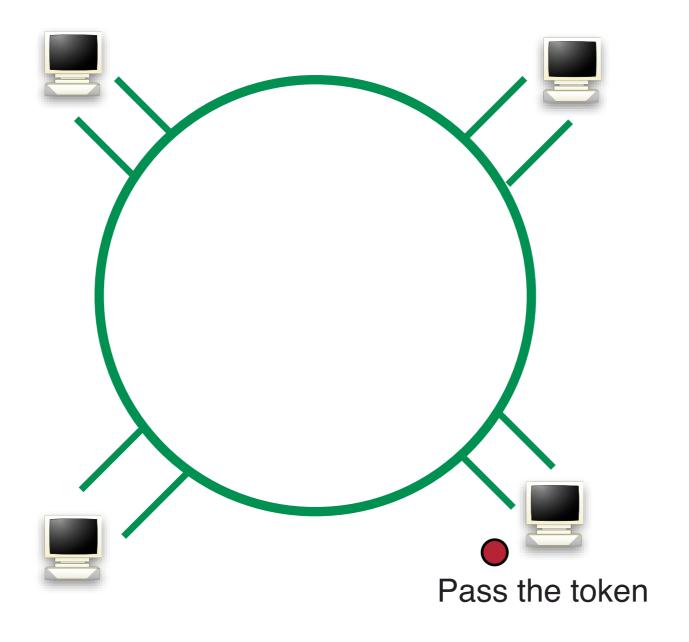




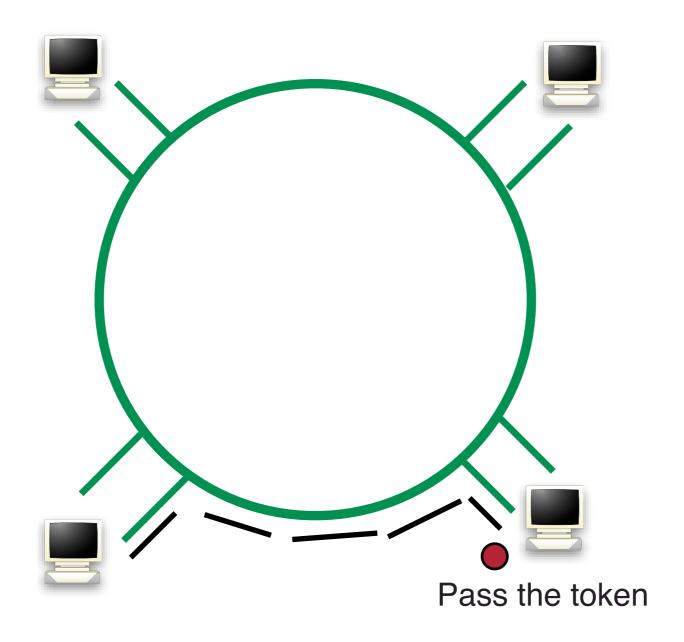




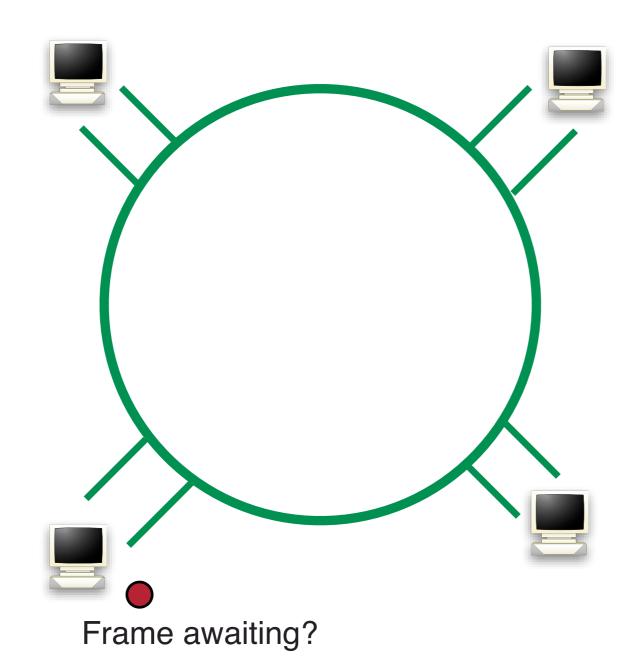




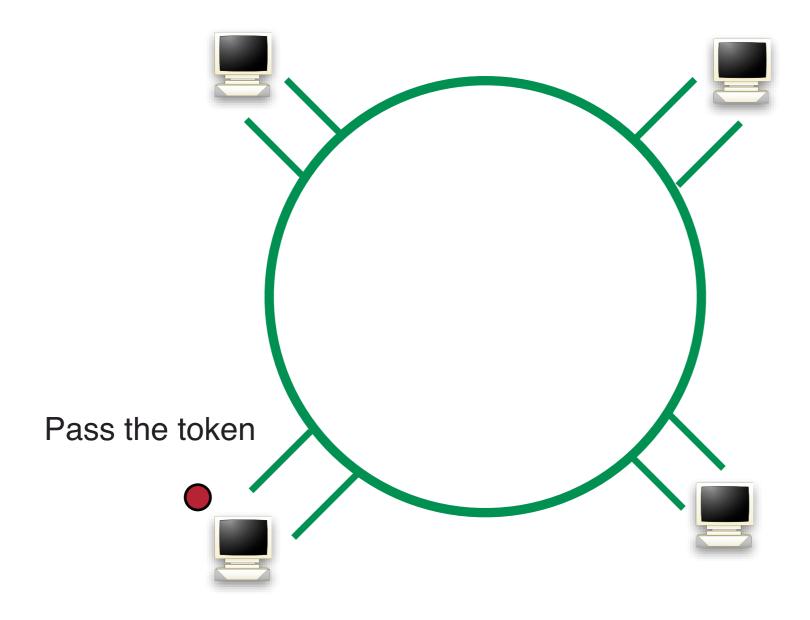




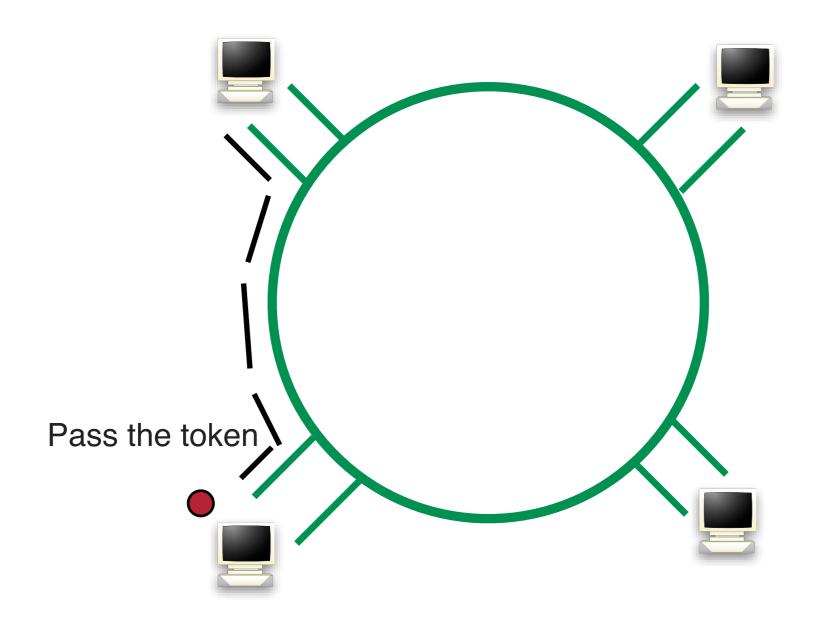




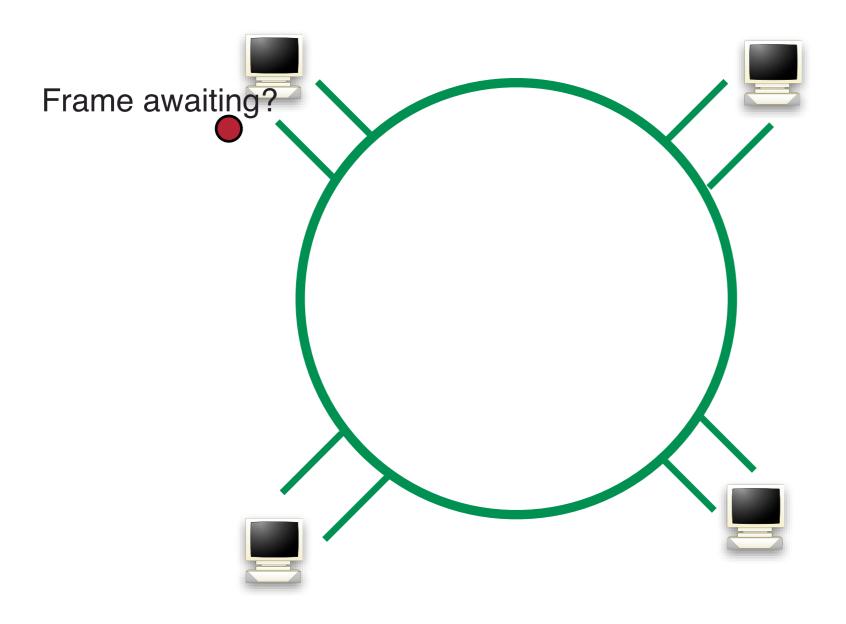






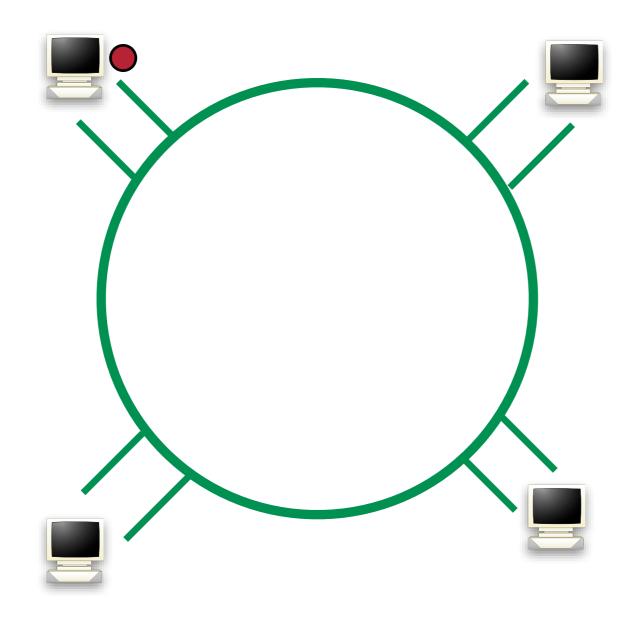






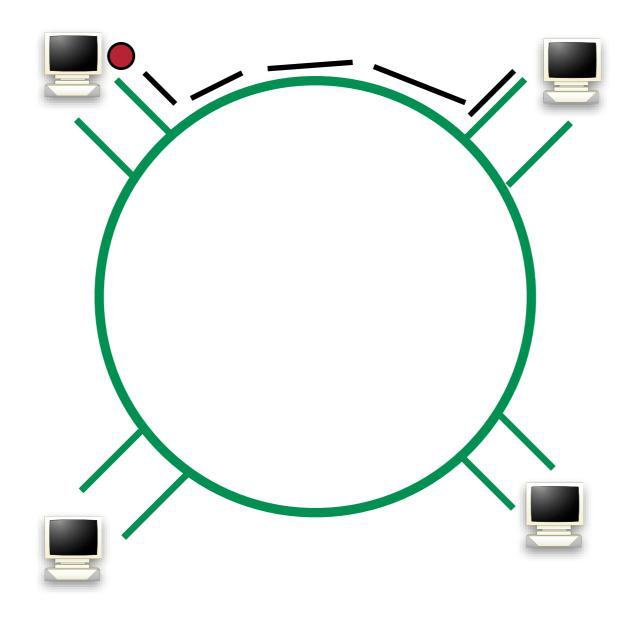








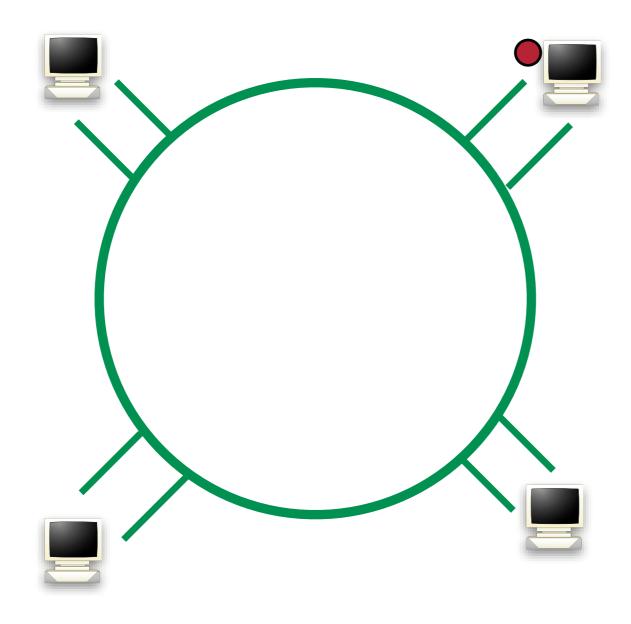






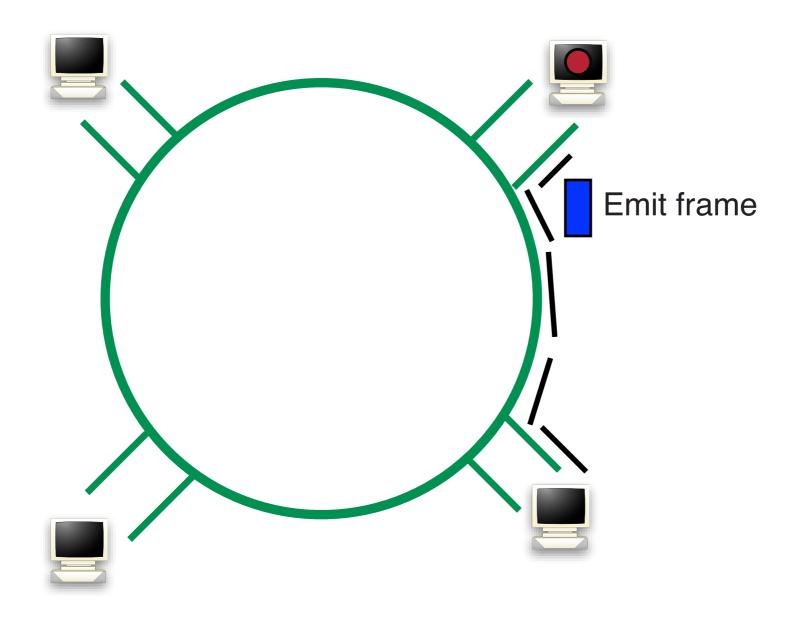


Frame awaiting?

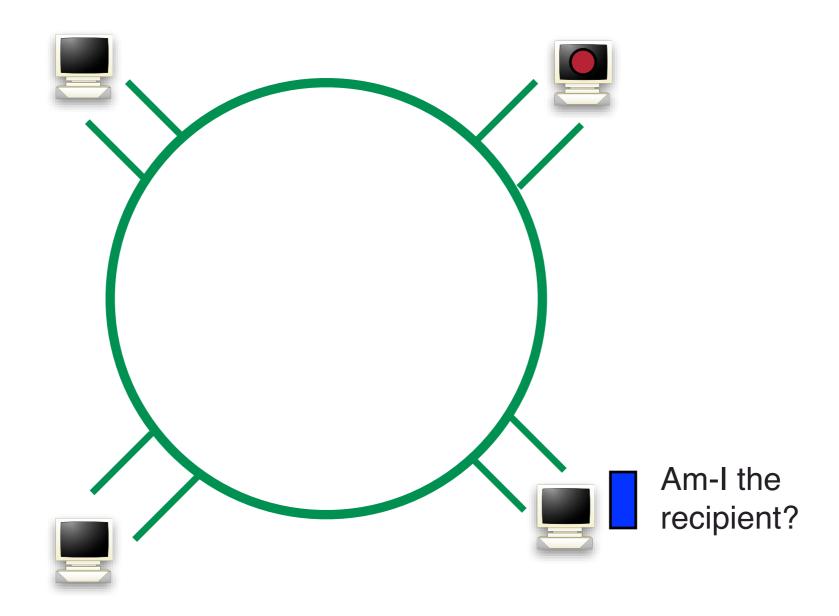




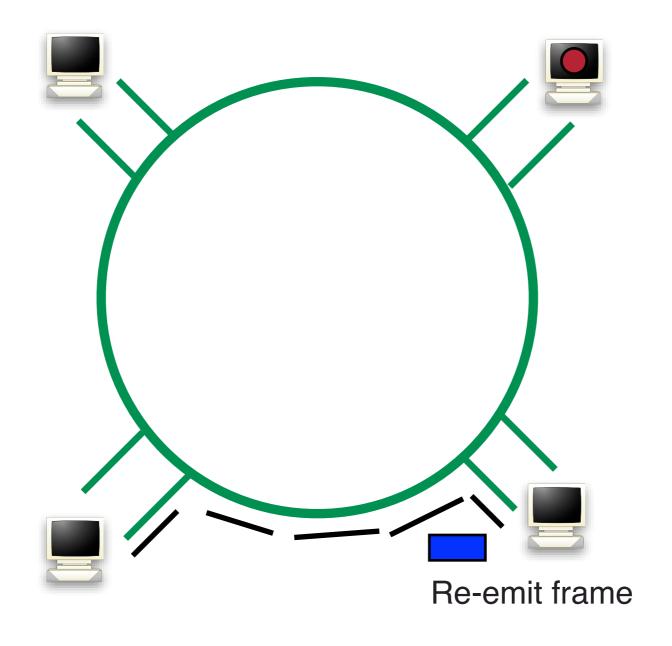




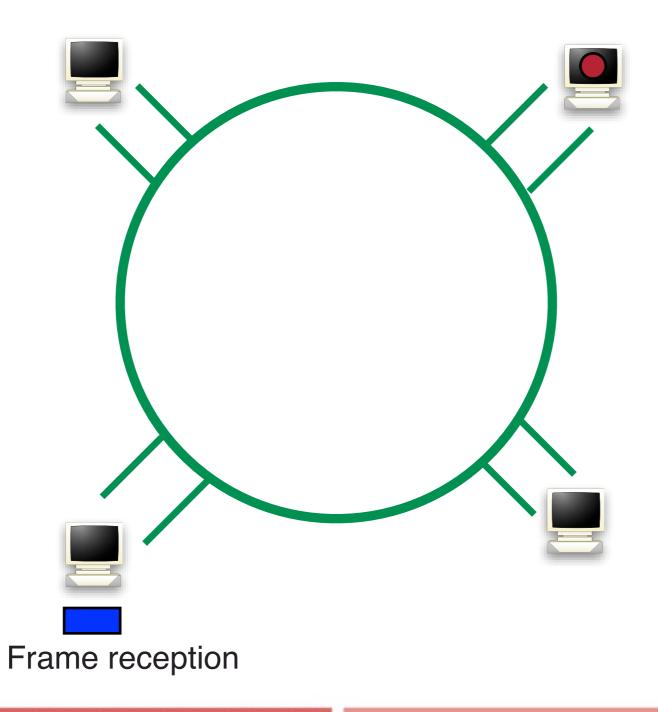




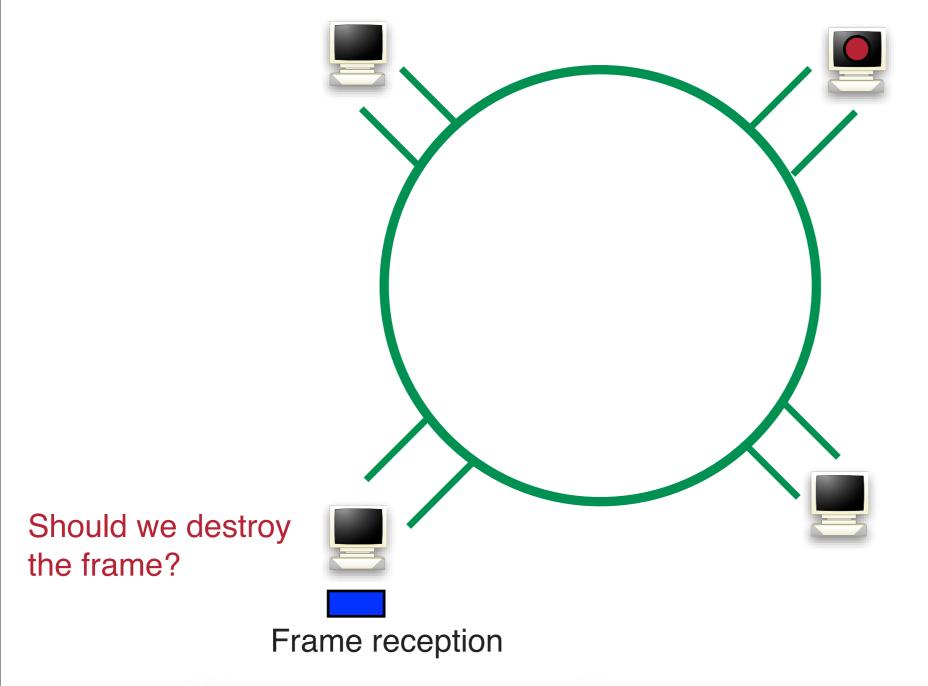






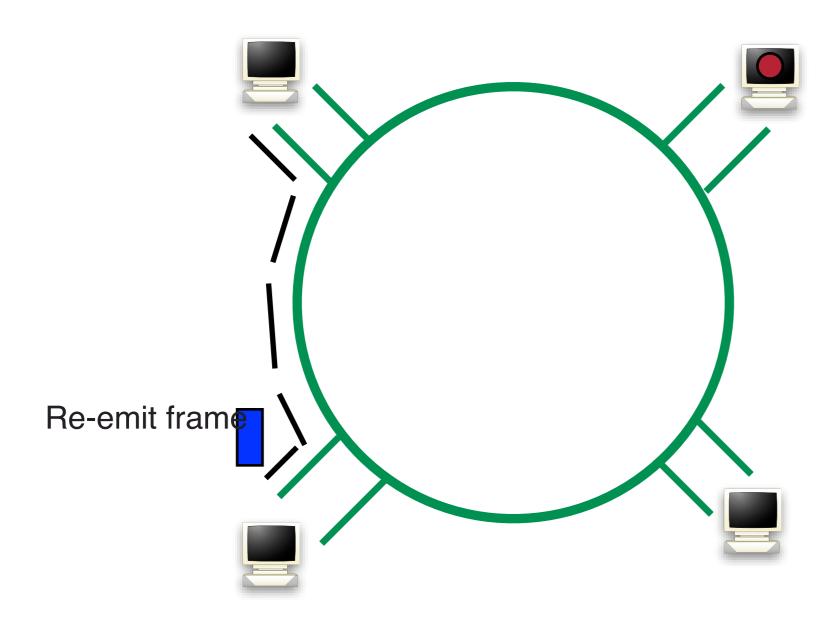








問題響

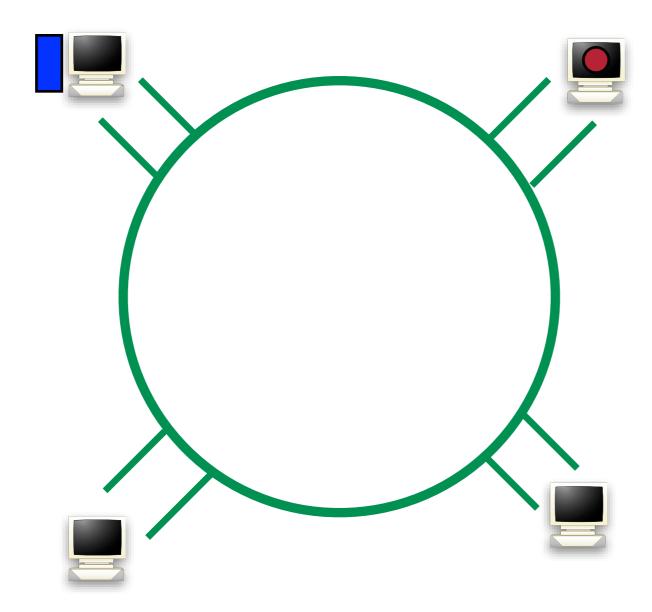




一般星级

Frames circulation

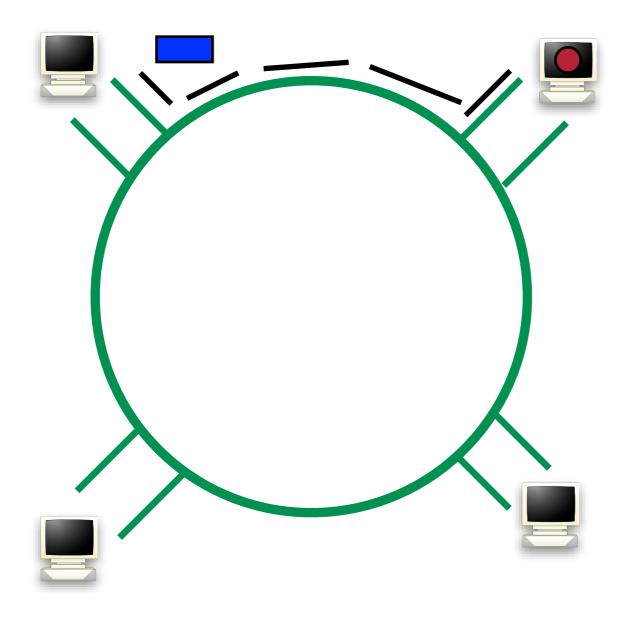
Am-I the recipient?





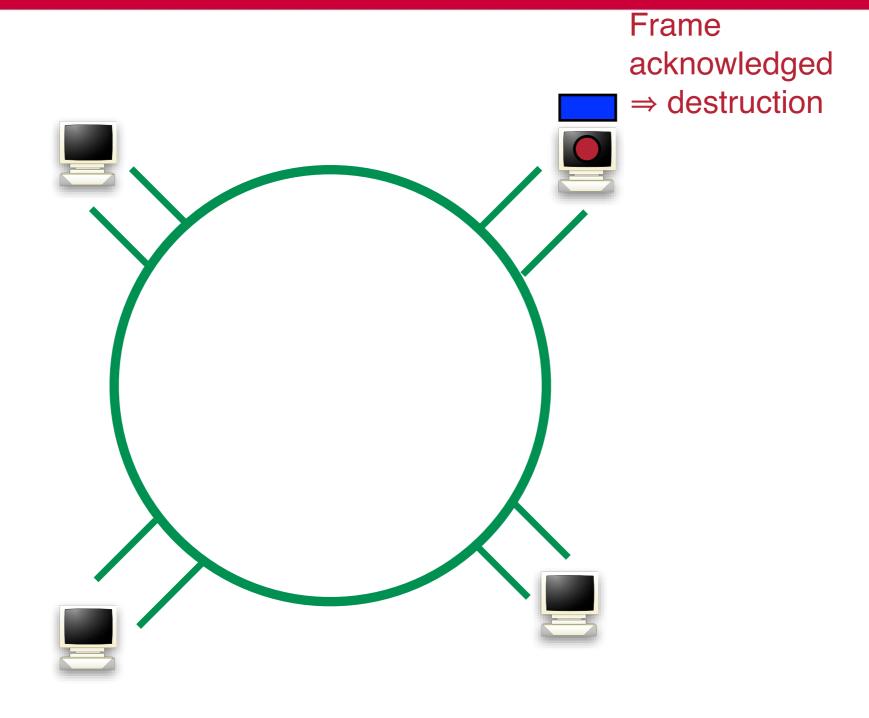


Re-emit frame



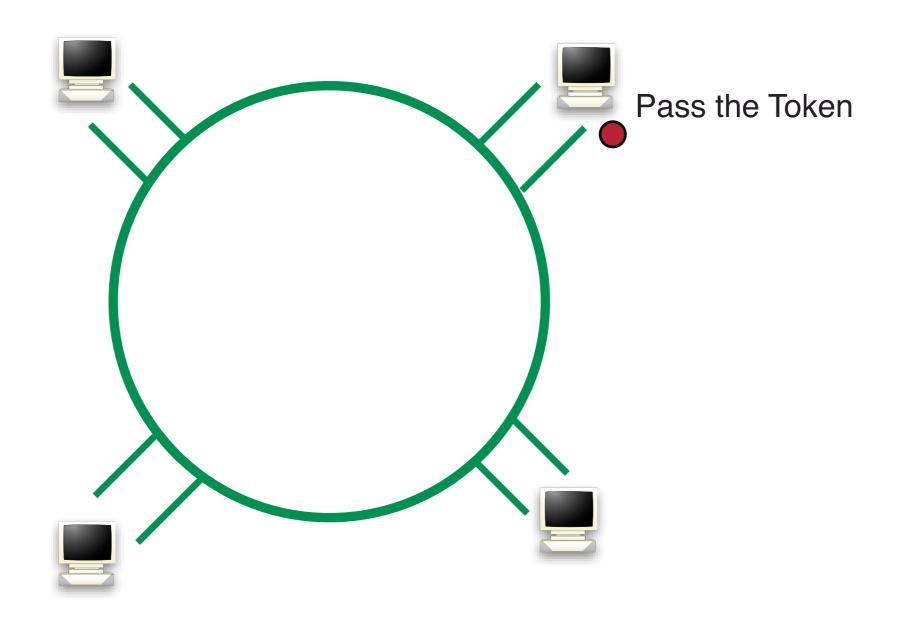


問題経



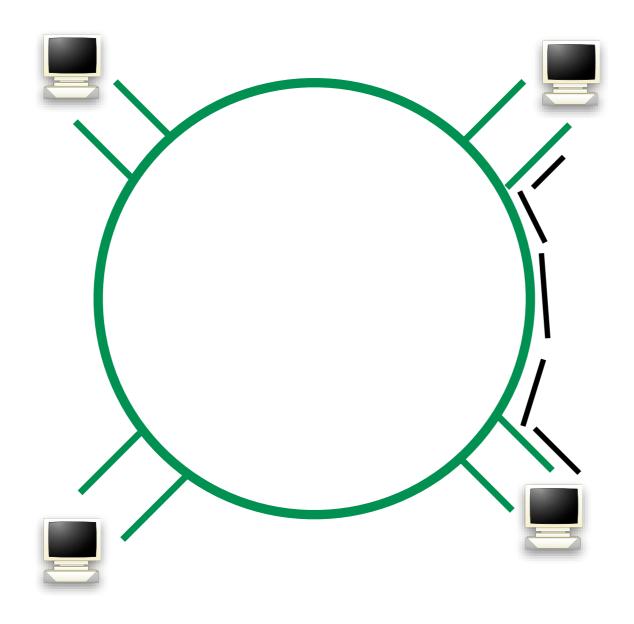


粉製器

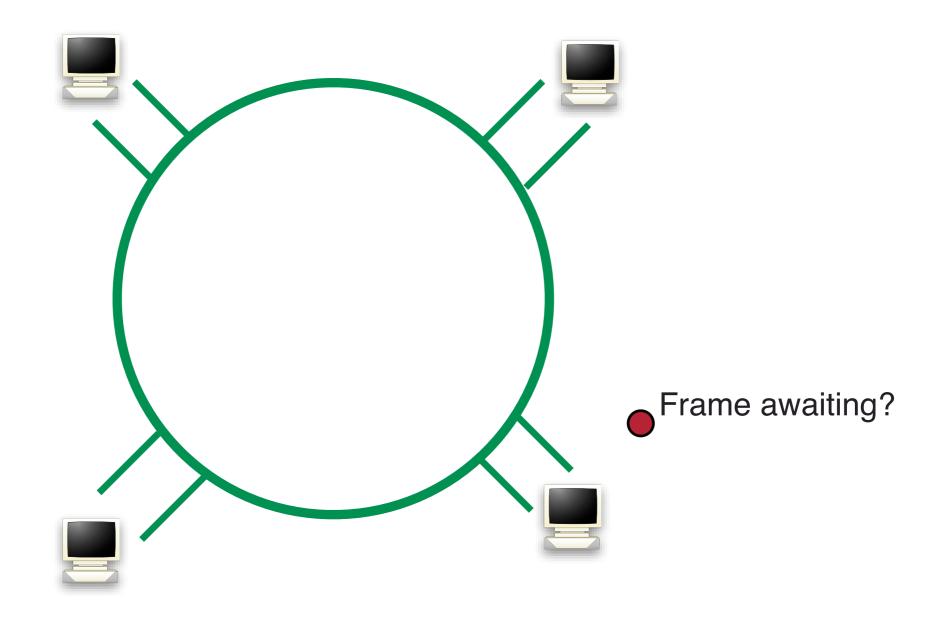














Ring management

Initialization

- A token is necessary to start the transmissions, who generates it?
 - Use of a particular node: the monitor

Device failure

- The ring is cut if one station fails
 - How to detect stations failures?
 - Previous and next stations send the traffic in the opposite direction
- If the station possessed the token when it failed?
 - The monitor is in charge of re-generating the token
- What if the monitor fails?
 - Election / re-election of a monitor among the stations



Ethernet-Token Ring comparison

- Performance calculation: see exercises session
- Low-load performance reduced because of token passing
- Scalability much better than Ethernet
 - Constant overhead, no collisions

